

## PROBLEMS

**PROBLEM 1.** Find a complete integral of the Hamilton–Jacobi equation for motion of a particle in a field  $U = \alpha/r - Fz$  (a combination of a Coulomb field and a uniform field), and find a conserved function of the co-ordinates and momenta that is specific to this motion.

**SOLUTION.** The field is of the type (48.15), with  $a(\xi) = \alpha - \frac{1}{2}F\xi^2$ ,  $b(\eta) = \alpha + \frac{1}{2}F\eta^2$ . The complete integral of the Hamilton–Jacobi equation is given by (48.16) with these functions  $a(\xi)$  and  $b(\eta)$ . To determine the significance of the constant  $\beta$ , we write the equations

$$2\xi p_\xi^2 + ma(\xi) - mE\xi + \frac{1}{2}p_\xi^2 \xi = \beta,$$

$$2\eta p_\eta^2 + mb(\eta) - mE\eta + \frac{1}{2}p_\eta^2 \eta = -\beta.$$

Subtracting, and expressing the momenta  $p_\xi = \partial S/\partial \xi$  and  $p_\eta = \partial S/\partial \eta$  in terms of the momenta  $p = \partial S/\partial \rho$  and  $p_z = \partial S/\partial z$  in cylindrical co-ordinates, we obtain after a simple calculation

$$\beta = -m \left[ \frac{\alpha z}{r} + \frac{p_z}{m} (z p_r - \rho p_z) + \frac{p_\phi^2}{m \rho^2} z \right] - \frac{1}{2} m F \rho^2.$$

The expression in the brackets is an integral of the motion that is specific to the pure Coulomb field (the  $z$ -component of the vector (15.17)).

**PROBLEM 2.** The same as Problem 1, but for a field  $U = \alpha_1/r_1 + \alpha_2/r_2$  (the Coulomb field of two fixed points at a distance  $2\sigma$  apart).

**SOLUTION.** This field is of the type (48.21), with  $a(\xi) = (\alpha_1 + \alpha_2)\xi/\sigma$ ,  $b(\eta) = (\alpha_1 - \alpha_2)\eta/\sigma$ . The action  $S(\xi, \eta, \varphi, t)$  is obtained by substituting these expressions in (48.22). The significance of the constant  $\beta$  is found in a manner similar to that in Problem 1; in this case it expresses the conservation of the quantity

$$\beta = \sigma^2 \left( p^2 + \frac{p_\phi^2}{\rho^2} \right) - M^2 + 2m\sigma(\alpha_1 \cos \theta_1 + \alpha_2 \cos \theta_2),$$

$$M^2 = (\mathbf{r} \times \mathbf{p})^2$$

$$= p^2 z^2 + p_z^2 \rho^2 + \frac{r^2 p_\phi^2}{\rho^2} - 2z\rho p_r p_\phi,$$

and  $\theta_1$  and  $\theta_2$  are the angles shown in Fig. 55.

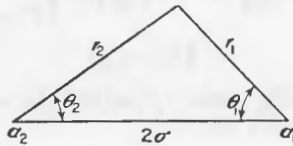


FIG. 55

## §49. Adiabatic invariants

Let us consider a mechanical system executing a finite motion in one dimension and characterised by some parameter  $\lambda$  which specifies the properties of the system or of the external field in which it is placed,† and let us suppose that  $\lambda$  varies slowly (*adiabatically*) with time as the result of some external action; by a “slow” variation we mean one in which  $\lambda$  varies only slightly during the period  $T$  of the motion:

$$T \, d\lambda/dt \ll \lambda. \quad (49.1)$$

† To simplify the formulae, we assume that there is only one such parameter, but all the results remain valid for any number of parameters.

If  $\lambda$  were constant, the system would be closed and would execute a strictly periodic motion with a constant energy  $E$  and a fixed period  $T(E)$ . When the parameter  $\lambda$  is variable, the system is not closed and its energy is not conserved. However, since  $\lambda$  is assumed to vary only slowly, the rate of change  $\dot{E}$  of the energy will also be small. If this rate is averaged over the period  $T$  and the "rapid" oscillations of its value are thereby smoothed out, the resulting value  $\bar{E}$  determines the rate of steady slow variation of the energy of the system, and this rate will be proportional to the rate of change  $\dot{\lambda}$  of the parameter. In other words, the slowly varying quantity  $E$ , taken in this sense, will behave as some function of  $\lambda$ . The dependence of  $E$  on  $\lambda$  can be expressed as the constancy of some combination of  $E$  and  $\lambda$ . This quantity, which remains constant during the motion of a system with slowly varying parameters, is called an *adiabatic invariant*.

Let  $H(q, p; \lambda)$  be the Hamiltonian of the system, which depends on the parameter  $\lambda$ . According to formula (40.5), the rate of change of the energy of the system is

$$\frac{dF}{dt} = \frac{\partial H}{\partial t} = \frac{\partial H}{\partial \lambda} \frac{d\lambda}{dt}. \quad (49.2)$$

The expression on the right depends not only on the slowly varying quantity  $\lambda$  but also on the rapidly varying quantities  $q$  and  $p$ . To ascertain the steady variation of the energy we must, according to the above discussion, average (49.2) over the period of the motion. Since  $\lambda$  and therefore  $\dot{\lambda}$  vary only slowly, we can take  $\dot{\lambda}$  outside the averaging:

$$\frac{d\bar{E}}{dt} = \frac{d\lambda}{dt} \frac{\partial \bar{H}}{\partial \lambda}, \quad (49.3)$$

and in the function  $\partial H/\partial \lambda$  being averaged we can regard only  $q$  and  $p$ , and not  $\lambda$ , as variable. In other words, the averaging is taken over the motion which would occur if  $\lambda$  remained constant.

The averaging may be explicitly written

$$\frac{\partial \bar{H}}{\partial \lambda} = \frac{1}{T} \int_0^T \frac{\partial H}{\partial \lambda} dt.$$

According to Hamilton's equation  $\dot{q} = \partial H/\partial p$ , or  $dt = dq \div (\partial H/\partial p)$ . The integration with respect to time can therefore be replaced by one with respect to the co-ordinate, with the period  $T$  written as

$$T = \int_0^T dt = \oint dq \div (\partial H/\partial p); \quad (49.4)$$

here the  $\oint$  sign denotes an integration over the complete range of variation ("there and back") of the co-ordinate during the period.† Thus (49.3) becomes

$$\frac{\overline{dE}}{dt} = \frac{d\lambda \oint (\partial H / \partial \lambda) dq / (\partial H / \partial p)}{\oint dq / (\partial H / \partial p)} \quad (49.5)$$

As has already been mentioned, the integrations in this formula must be taken over the path for a given constant value of  $\lambda$ . Along such a path the Hamiltonian has a constant value  $E$ , and the momentum is a definite function of the variable co-ordinate  $q$  and of the two independent constant parameters  $E$  and  $\lambda$ . Putting therefore  $p = p(q; E, \lambda)$  and differentiating with respect to  $\lambda$  the equation  $H(q, p, \lambda) = E$ , we have  $\partial H / \partial \lambda + (\partial H / \partial p)(\partial p / \partial \lambda) = 0$ , or

$$\frac{\partial H / \partial \lambda}{\partial H / \partial p} = -\frac{\partial p}{\partial \lambda}$$

Substituting this in the numerator of (49.5) and writing the integrand in the denominator as  $\partial p / \partial E$ , we obtain

$$\frac{\overline{dE}}{dt} = -\frac{d\lambda \oint (\partial p / \partial \lambda) dq}{dt \oint (\partial p / \partial E) dq}$$

or

$$\oint \left( \frac{\partial p}{\partial E} \frac{\overline{dE}}{dt} + \frac{\partial p}{\partial \lambda} \frac{d\lambda}{dt} \right) dq = 0.$$

Finally, this may be written as

$$\overline{dI/dt} = 0, \quad (49.6)$$

where

$$I \equiv \oint p dq / 2\pi, \quad (49.7)$$

the integral being taken over the path for given  $E$  and  $\lambda$ . This shows that, in the approximation here considered,  $I$  remains constant when the parameter  $\lambda$  varies, i.e.  $I$  is an adiabatic invariant.

The quantity  $I$  is a function of the energy of the system (and of the parameter  $\lambda$ ). The partial derivative with respect to energy determines the period of the motion: from (49.4),

$$2\pi \frac{\partial I}{\partial E} = \oint \frac{\partial p}{\partial E} dq = T \quad (49.8)$$

† If the motion of the system is a rotation, and the co-ordinate  $q$  is an angle of rotation  $\phi$ , the integration with respect to  $\phi$  must be taken over a "complete rotation", i.e. from 0 to  $2\pi$ .

or

$$\partial E / \partial I = \omega, \quad (49.9)$$

where  $\omega = 2\pi/T$  is the vibration frequency of the system.

The integral (49.7) has a geometrical significance in terms of the phase path of the system. In the case considered (one degree of freedom), the phase space reduces to a two-dimensional space (i.e. a plane) with co-ordinates  $p, q$ , and the phase path of a system executing a periodic motion is a closed curve in the plane. The integral (49.7) taken round this curve is the area enclosed. It can be written also as the area integral

$$I = \iint dp dq / 2\pi. \quad (49.10)$$

As an example, let us determine the adiabatic invariant for a one-dimensional oscillator. The Hamiltonian is

$$H = \frac{1}{2}p^2/m + \frac{1}{2}m\omega^2q^2, \quad (49.11)$$

where  $\omega$  is the eigenfrequency of the oscillator. The equation of the phase path is given by the law of conservation of energy  $H(p, q) = E$ . The path is an ellipse with semi-axes  $\sqrt{2mE}$  and  $\sqrt{2E/m\omega^2}$ , and its area, divided by  $2\pi$ , is

$$I = E/\omega. \quad (49.12)$$

The adiabatic invariance of  $I$  signifies that, when the parameters of the oscillator vary slowly, the energy is proportional to the frequency.

## §50. Canonical variables

Now let the parameter  $\lambda$  be constant, so that the system in question is closed. Let us effect a canonical transformation of the variables  $q$  and  $p$ , taking  $I$  as the new "momentum". The generating function is the abbreviated action  $S_0$ , expressed as a function of  $q$  and  $I$ . For  $S_0$  is defined as the integral

$$S_0(q, E; \lambda) = \int p(q, E; \lambda) dq, \quad (50.1)$$

taken for a given energy  $E$  and parameter  $\lambda$ . For a closed system, however,  $I$  is a function of the energy alone, and so  $S_0$  can equally well be written as a function  $S_0(q, I; \lambda)$ , and the partial derivative  $(\partial S_0 / \partial q)_E$  is the same as the derivative  $(\partial S_0 / \partial q)_I$  for constant  $I$ . Hence

$$p = \partial S_0(q, I; \lambda) / \partial q, \quad (50.2)$$

corresponding to the first of the formulae (45.8) for a canonical transformation. The second of these formulae gives the new "co-ordinate", which we denote by  $w$ :

$$w = \partial S_0(q, I; \lambda) / \partial I. \quad (50.3)$$

The variables  $I$  and  $w$  are called *canonical variables*;  $I$  is called the *action variable* and  $w$  the *angle variable*.